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On the L^q -saturation property for functions from $W^{2,p}(\Omega)$

Abdellatif Agouzal^a, Yuri V. Vassilevski^{b,*}

^a U.M.R. 5585–Université Lyon 1, Laboratoire d'Analyse Numérique Bat. 101, 69 622 Villeurbanne Cedex, France ^b Institute of Numerical Mathematics, Russian Academy of Sciences, Gubkina st. 8, Moscow 119333, Russia

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ABSTRACT

This short note is devoted to the proof of the L^q -saturation property for functions from the Sobolev space $W^{2,p}(\Omega)$, p > d/2, on sequences of conformal, possibly anisotropic, simplicial meshes for spaces of arbitrary dimension d. The proof completes the theory of optimal meshes minimizing the L^q -error ($0 < q \le p$) of P_1 -interpolation and the theory of quasi-optimal meshes which are achievable approximations of the optimal meshes (Agouzal et al., 2009, 2010 [2,3], Agouzal et al., 2010 [4]).

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Applied Mathematics

Letters

1. Prerequisites

Let $\Omega \subset \mathbb{R}^d$ be a bounded polyhedral domain and \mathcal{T}_N be a conformal simplicial mesh with *N d*-simplexes. The volume of a *d*-simplex Δ and its diameter are denoted by $|\Delta|$ and diam (Δ) , respectively. The vertices of Δ are denoted by \mathbf{v}_i , $i = 1, \ldots, d + 1$. We define $h_N = \sup_{\Delta \in \mathcal{T}_N} \operatorname{diam}(\Delta)$ and consider a sequence of meshes \mathcal{T}_N such that $N \to \infty$.

Let $\mathcal{I}_N^1 u(\mathcal{I}_N^2 u)$ be the continuous piecewise linear (quadratic) interpolant of a continuous function u on a mesh \mathcal{T}_N , and $\mathcal{I}_A^1 u(\mathcal{I}_A^2 u)$ be its restriction to Δ . In particular,

$$(\boldsymbol{l}_{\Delta}^{1}\boldsymbol{u})(\mathbf{x}) = \sum_{i=1}^{d+1} \boldsymbol{u}(\mathbf{v}_{i})\lambda_{i}(\mathbf{x}), \quad \mathbf{x} \in \Delta,$$

where $\lambda_i(\mathbf{x})$, i = 1, ..., d + 1 are linear functions on Δ such that $\lambda_i(\mathbf{v}_j) = \delta_{ij}$, δ_{ij} is the Kronecker symbol.

In this note we shall deal with functions u from the Sobolev space $W^{2,p}(\Omega)$ for p > d/2. Due to the embedding theorem, they are continuous functions and therefore the conventional Lagrange interpolation can be defined for them. Each entry $H_{ij}(\mathbf{x})$ of the Hessian matrix $H(\mathbf{x})$ of u is a function from $L^p(\Omega)$. The space $W^{2,p}(\Omega)$, p > d/2, is feasible for applications. For instance, the solution u of the Poisson equation in a 2D domain with piecewise smooth boundary (d = 2) has the singular part $\phi(r, \theta)r^{\alpha}$, $\alpha \in [\frac{1}{2}; 1[$, in a local polar coordinate system [1]. Therefore, $u \in W^{1+\alpha,2}(\Omega)$ and $u \in W^{2,p}(\Omega)$ for any $1 \le p < 2/(2 - \alpha)$, i.e. $u \in W^{2,\frac{4}{3}-\epsilon}(\Omega)$ for a small $\epsilon > 0$.

The L^q -saturation property, in its simple form, asserts that a smooth function can be approximated asymptotically better with its piecewise quadratic interpolant than with its piecewise linear interpolant. More precisely, there exists $\alpha \in]0, 1[$ such that, for any function $u \in W^{2,p}(\Omega)$ and sequences of meshes $\mathcal{T}_N, N \to \infty$, one has for $0 < q \leq p$:

$$\frac{\|u - \mathscr{l}_N^2 u\|_{L^q(\Omega)}}{\|u - \mathscr{l}_N^1 u\|_{L^q(\Omega)}} \le \alpha.$$

$$\tag{1}$$

* Corresponding author. Tel.: +7 9175061751.

E-mail addresses: agouzal@univ-lyon1.fr (A. Agouzal), yuri.vassilevski@gmail.com (Y.V. Vassilevski).

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A. Agouzal, Y.V. Vassilevski / Applied Mathematics Letters 25 (2012) 2123-2127

The L^q -saturation property is used in the theory of optimal meshes minimizing the L^q -error ($0 < q \leq p$) of P_1 -interpolation and the theory of quasi-optimal meshes which are achievable approximations of the optimal meshes [2–4].

A more popular assumption is the $W^{1,q}$ -saturation property [5–8] where the L^q -norm in (1) is replaced by the $W^{1,q}$ -seminorm. It is widely used in the classical proof of equivalence of some a posteriori error estimators with the energy error although this property was shown to be superfluous in the case of isotropic meshes [6]. The analysis of the $W^{1,q}$ -saturation property on sequences of conformal, possibly anisotropic, simplicial meshes is the subject of future research. The analysis will complete the theory of optimal meshes minimizing the $W^{1,q}$ -error of P_1 -interpolation and the theory of corresponding quasi-optimal meshes [2–4,9].

In the sequel, we develop the proof of (1) and present the conditions for mesh sequences under which (1) holds.

2. Functions of two arguments and their properties

For a function of two arguments $v(\mathbf{x}, \mathbf{y})$ we introduce a broken norm in Ω

$$[v]_{p,\Omega}^{p} = \sum_{\Delta \in \mathcal{T}_{N}} [v]_{p,\Delta}^{p}, \quad [v]_{p,\Delta}^{p} = |\Delta|^{-1} \int_{\Delta} \int_{\Delta} |v(\mathbf{x}, \mathbf{y})|^{p} d\mathbf{x} d\mathbf{y}.$$
⁽²⁾

For functions with one argument, the broken *p*-norm coincides with the L^p -norm. If *v* is continuous in Ω with respect to the first argument, we can define the P_1 Lagrange interpolation $\mathcal{I}_N^1 v$ via its restriction $\mathcal{I}_\Delta^1 v$ on Δ

$$\mathcal{I}_{\Delta}^{1} v(\mathbf{x}, \mathbf{y}) = \sum_{i=1}^{d+1} v(\mathbf{v}_{i}, \mathbf{y}) \lambda_{i}(\mathbf{x}).$$
(3)

We shall consider two functions of two arguments,

$$\pi(\mathbf{x}, \mathbf{y}) = u(\mathbf{y}) + \nabla u \cdot (\mathbf{x} - \mathbf{y}) + \frac{1}{2} (H(\mathbf{y})(\mathbf{x} - \mathbf{y}), \mathbf{x} - \mathbf{y}),$$
(4)

(5)

$$\omega(\mathbf{x}, \mathbf{y}) = \|H(\mathbf{x}) - H(\mathbf{y})\|_{\mathbf{x}}$$

where the difference of the Hessians is evaluated in the spectral norm.

Lemma 1. For any conformal triangulation \mathcal{T}_N and any $u \in W^{2,q}(\Omega)$, q > 0, it holds:

$$C(d,q)^{\frac{1}{q}} \|\det H\|_{L^{\frac{q}{2q+d}}(\Omega)}^{\frac{1}{d}} \le N^{\frac{2}{d}} [\pi - \mathcal{I}_{N}^{1}\pi]_{q,\Omega}$$
(6)

where C(d, q) is a positive constant depending on d and q only. **Proof.** Let

$$t = \frac{q}{2q+d}, \qquad r = 1 + \frac{2q}{d}, \qquad s = 1 + \frac{d}{2q}, \qquad \beta = \frac{2q}{2q+d}$$

for which it holds:

$$tr = \frac{q}{d}, \qquad \beta r = \frac{2q}{d}, \qquad \beta s = 1.$$

Using the Hölder inequality, $|\det H|^t = (|\det H|^t |\Delta|^\beta) |\Delta|^{-\beta}$ and the fact that

$$\sum_{\Delta \in \mathcal{T}_N} \int_{\Delta} |\Delta|^{-1} \mathrm{d}\mathbf{x} = N$$

we obtain

$$\int_{\Omega} |\det H(\mathbf{y})|^{t} d\mathbf{y} \leq \left(\sum_{\Delta \in \mathcal{T}_{N}} \int_{\Delta} |\det H(\mathbf{y})|^{\frac{q}{d}} |\Delta|^{\frac{2q}{d}} d\mathbf{y} \right)^{\frac{1}{r}} N^{\frac{1}{s}}.$$
(7)

Let us show that there exists such a positive constant C(d, q) that

$$C(d,q)\int_{\Delta} |\det H(\mathbf{y})|^{\frac{q}{d}} |\Delta|^{\frac{2q}{d}} d\mathbf{y} \leq [\pi - \mathcal{I}_{\Delta}^{1}\pi]_{q,\Delta}^{q}.$$
(8)

Indeed, π is a quadratic function in **x** and due to (3) it is sufficient to analyze functions $\pi_M = \frac{1}{2}(M\mathbf{x}, \mathbf{x})$ for any symmetric nonsingular matrix M of order d on any d-simplex. We consider the matrix $\widehat{M} = |\det M|^{-\frac{1}{d}}M$, such that $|\det \widehat{M}| = 1$, and the d-simplex $\widehat{\Delta} = \{\widehat{\mathbf{x}} \mid \widehat{\mathbf{x}} = |\Delta|^{-\frac{1}{d}}\mathbf{x}, \mathbf{x} \in \Delta\}$, such that $|\widehat{\Delta}| = 1$. Then

$$\|\pi_{M} - \mathcal{I}_{\Delta}^{1} \pi_{M}\|_{L^{q}(\Delta)}^{q} = |\Delta|^{\frac{2q}{d}+1} |\det M|^{\frac{q}{d}} \|\pi_{\widehat{M}} - \mathcal{I}_{\widehat{\Delta}}^{1} \pi_{\widehat{M}}\|_{L^{q}(\widehat{\Delta})}^{q} \ge C(q,d) |\Delta|^{\frac{2q}{d}+1} |\det M|^{\frac{q}{d}},$$

where

$$C(q,d) := \inf_{|\det\widehat{M}|=1} \inf_{|\widehat{\Delta}|=1} \|\pi_{\widehat{M}} - \mathcal{I}_{\widehat{\Delta}}^{1} \pi_{\widehat{M}}\|_{L^{q}(\widehat{\Delta})}^{q}.$$

Averaging the last estimate over Δ , we get (8). Plugging (8) into (7) and using $r = \frac{q}{td}$, $\frac{r}{s} = \frac{2q}{d}$ we get (6). \Box We denote $\epsilon_N = [\omega(\mathbf{x}, \mathbf{y})]_{p,\Omega}$ which is the L^p modulus of continuity of $\omega(\mathbf{x}, \mathbf{y})$. It is well known that:

$$\lim_{h_N \to 0} \epsilon_N = 0. \tag{9}$$

Lemma 2. Let $u \in W^{2,p}(\Omega)$, p > d/2, $0 < q \le p$. Then

$$[u - \pi - \mathcal{I}_{N}^{1}(u - \pi)]_{q,\Omega} \le \frac{6p}{2p - d} h_{N}^{2} |\Omega|^{\frac{1}{q} - \frac{1}{p}} \epsilon_{N}.$$
(10)

Proof. Consider the function $v = u - \pi$ as a function of **x** argument. We have $v \in W^{2,p}(\Delta)$ and the Hessian of v is $H(\mathbf{x}) - H(\mathbf{y})$. According to [10] (p. 413, Theorems 2–1) it holds:

$$\|v - \pounds_{\Delta}^{1} v\|_{p,\Delta}^{p} \leq \left(\frac{6p}{2p-d}\right)^{p} (\operatorname{diam}\Delta)^{2p} \int_{\Delta} \|H(\mathbf{x}) - H(\mathbf{y})\|^{p} \mathrm{d}\mathbf{x}, \quad a.e. \, \mathbf{y} \in \Delta.$$

$$(11)$$

The definition of the broken norm implies that

$$[v - \mathbf{l}_{\Delta}^{1}v]_{p,\Delta} \leq \frac{6p}{2p-d}h_{N}^{2}[\omega(\mathbf{x},\mathbf{y})]_{p,\Delta}$$

and

$$[v - \mathbf{l}_{N}^{1}v]_{q,\Omega} \leq |\Omega|^{\frac{1}{q} - \frac{1}{p}} [v - \mathbf{l}_{N}^{1}v]_{p,\Omega} \leq |\Omega|^{\frac{1}{q} - \frac{1}{p}} \frac{6p}{2p - d} h_{N}^{2} [\omega(\mathbf{x}, \mathbf{y})]_{p,\Omega} = \frac{6p}{2p - d} |\Omega|^{\frac{1}{q} - \frac{1}{p}} h_{N}^{2} \epsilon_{N}. \quad \Box$$

The simple consequence of Lemmas 1 and 2 is the corollary.

Corollary 3. Under conditions of Lemma 2 it holds:

$$C(d,q)^{\frac{1}{q}} \|\det H\|_{L^{\frac{q}{2q+d}}(\Omega)}^{\frac{1}{d}} \le N^{\frac{2}{d}} \|u - \mathcal{I}_{N}^{1}u\|_{L^{q}(\Omega)} + \frac{6p}{2p-d} N^{\frac{2}{d}} h_{N}^{2} |\Omega|^{\frac{1}{q}-\frac{1}{p}} \epsilon_{N}.$$
(12)

Proof. Since $\pi - I_N^1 \pi = \pi - u - I_N^1 (\pi - u) + u - I_N^1 u$, we apply the triangular inequality to get from (6) and (10):

$$\begin{split} C(d,q)^{\frac{1}{q}} \|\det H\|_{L^{\frac{q}{2q+d}}(\Omega)}^{\frac{1}{d}} &\leq N^{\frac{2}{d}} \left([u - \mathcal{I}_{N}^{1}u]_{q,\Omega} + [\pi - u - \mathcal{I}_{N}^{1}(\pi - u)]_{q,\Omega} \right) \\ &\leq N^{\frac{2}{d}} \left([u - \mathcal{I}_{N}^{1}u]_{q,\Omega} + \frac{6p}{2p - d}h_{N}^{2}|\Omega|^{\frac{1}{q} - \frac{1}{p}}\epsilon_{N} \right) \\ &= N^{\frac{2}{d}} \left(\|u - \mathcal{I}_{N}^{1}u\|_{L^{q}(\Omega)} + \frac{6p}{2p - d}h_{N}^{2}|\Omega|^{\frac{1}{q} - \frac{1}{p}}\epsilon_{N} \right). \quad \Box \end{split}$$

3. Upper and lower bounds of interpolation errors

An upper bound for the P_2 -interpolation error can be established as follows.

Lemma 4. Let $u \in W^{2,p}(\Omega)$, p > d/2 and a conformal triangulation \mathcal{T}_N of Ω be given. Then for $0 < q \le p$ it holds:

$$\|u - \mathcal{I}_{N}^{2}u\|_{L^{q}(\Omega)} \leq \frac{12p}{2p-d} |\Omega|^{\frac{1}{q}-\frac{1}{p}} h_{N}^{2} \epsilon_{N}.$$
(13)

Proof. The proof is based on the local estimate [10], (p. 413, Theorems 2–1) valid for any *d*-simplex $\Delta \in \mathcal{T}_N$:

$$\|u - \mathscr{I}_{\Delta}^{2} u\|_{L^{p}(\Delta)}^{p} \leq \left(\frac{12p}{2p-d}\right)^{p} (\operatorname{diam}\Delta)^{2p} \int_{\Delta} \|H(\mathbf{x})\|^{p} d\mathbf{x}.$$
(14)

Since $\pi(\mathbf{x}, \mathbf{y})$ is the quadratic function of argument \mathbf{x} and its Hessian with respect to \mathbf{x} is $H(\mathbf{y})$, we have

$$\|u - \boldsymbol{\mathcal{I}}_{\Delta}^{2} u\|_{L^{p}(\Delta)}^{p} = \|u - \pi - \boldsymbol{\mathcal{I}}_{\Delta}^{2} (u - \pi)\|_{L^{p}(\Delta)}^{p} \leq \left(\frac{12p}{2p - d}\right)^{p} (\operatorname{diam}\Delta)^{2p} \int_{\Delta} \|H(\mathbf{x}) - H(\mathbf{y})\|^{p} \mathrm{d}\mathbf{x}, \quad a.e. \, \mathbf{y} \in \Delta.$$

Averaging over Δ we obtain

$$\|u - \mathscr{L}_{\Delta}^{2} u\|_{L^{p}(\Delta)}^{p} \leq \left(\frac{12p}{2p-d}\right)^{p} (\operatorname{diam} \Delta)^{2p} \frac{1}{|\Delta|} \int_{\Delta} \int_{\Delta} \|H(\mathbf{x}) - H(\mathbf{y})\|^{p} d\mathbf{x} d\mathbf{y},$$

and summing over all $\Delta \in \mathcal{T}_N$ we get

$$\begin{split} \|u - \mathcal{I}_{\Delta}^{2} u\|_{L^{q}(\Omega)} &= [u - \mathcal{I}_{\Delta}^{2} u]_{q,\Omega} \leq |\Omega|^{\frac{1}{q} - \frac{1}{p}} [u - \mathcal{I}_{\Delta}^{2} u]_{p,\Omega} \\ &= |\Omega|^{\frac{1}{q} - \frac{1}{p}} \|u - \mathcal{I}_{\Delta}^{2} u\|_{L^{p}(\Omega)} \leq \frac{12p}{2p - d} |\Omega|^{\frac{1}{q} - \frac{1}{p}} h_{N}^{2} [\omega(\mathbf{x}, \mathbf{y})]_{p,\Omega}. \quad \Box \end{split}$$

The properties of functions of two arguments, the estimate (12) for the interpolation error and the upper bound for the P_2 -interpolation (14) do not impose any restrictions on triangulation \mathcal{T}_N but conformity. The lower bound for the P_1 -interpolation imposes a restriction on the sequence of meshes \mathcal{T}_N , $N \to \infty$, which we shall refer to as *condition A*.

Definition 1. The mesh sequence T_N , $N \to \infty$, satisfies condition A if there exist constants $\sigma > 0$ and $0 < \gamma < 1/2$ such that

$$h_N \epsilon_N^{\gamma} \le \sigma N^{-\frac{1}{d}}.$$
(15)

We recall that $\lim_{h_N\to 0} \epsilon_N = 0$ for any $u \in W^{2,p}(\Omega)$. For a sequence of meshes satisfying *condition A*, $\lim_{N\to\infty} \epsilon_N = 0$ although h_N does not necessarily tend to 0 as $N \to \infty$. Indeed, assume that there exists a subsequence denoted by $\{(\epsilon_N, h_N)\}_N$ such that for $N \ge N_0$ one has $\epsilon_N \ge a > 0$. Then from (15) $h_N \le \sigma N^{-\frac{1}{d}} a^{-\gamma}$ and $\lim_{N\to\infty} h_N = 0$. Therefore, for this subsequence $\lim_{N\to\infty} \epsilon_N = 0$ which is a contradiction.

We note that the class of meshes satisfying *condition* A is wide enough. It includes all quasiuniform meshes and \mathfrak{M} -quasiuniform meshes where \mathfrak{M} is a given tensor metric field. In particular, the meshes may be adaptive and possibly anisotropic [3,4,9,11].

The lower bound for the P₁-interpolation error is derived for mesh sequences satisfying condition A.

Lemma 5. Let $u \in W^{2,p}(\Omega)$, p > d/2 and a sequence of conformal triangulations \mathcal{T}_N satisfying condition A be given. Then for $0 < q \le p$ it holds:

$$C(d,q)^{\frac{1}{q}} \|\det H\|_{L^{\frac{1}{2q+d}}(\Omega)}^{\frac{1}{d}} \le \lim_{N \to \infty} N^{\frac{2}{d}} \|u - \mathcal{L}_{N}^{1}u\|_{L^{q}(\Omega)}.$$
(16)

Proof. From Corollary 3 and (15) one has

$$C(d,q)^{\frac{1}{q}} \|\det H\|_{L^{\frac{q}{2q+d}}(\Omega)}^{\frac{1}{d}} \le N^{\frac{2}{d}} \|u - \mathcal{I}_{N}^{1}u\|_{L^{q}(\Omega)} + \frac{6p\sigma^{2}}{2p-d} |\Omega|^{\frac{1}{q}-\frac{1}{p}} \epsilon_{N}^{1-2\gamma}.$$

Since $\gamma < 1/2$ and $\lim_{N \to \infty} \epsilon_N = 0$, we obtain (16). \Box

4. The *L^q*-saturation property

Theorem 6. Let $u \in W^{2,p}(\Omega)$, p > d/2 and a sequence of conformal triangulations \mathcal{T}_N satisfying condition A be given. Then for $0 < q \le p$ it holds:

$$\lim_{N \to \infty} \frac{\|u - I_N^2 u\|_{L^q(\Omega)}}{\|u - I_N^1 u\|_{L^q(\Omega)}} = 0.$$
(17)

Proof. Due to Lemma 4 and (15) there exists a positive constant C_2 depending on p, q, Ω , d only such that

$$\|u-\mathfrak{l}_{N}^{2}u\|_{L^{q}(\Omega)}\leq C_{2}(p,q,\Omega,d)N^{-\frac{2}{d}}\epsilon_{N}^{1-2\gamma}.$$

Due to Lemma 5 there exist a positive constant C_1 depending on u, q, Ω , d only and an integer N_0 such that for $N \ge N_0$ it holds:

$$C_1(u, q, \Omega, d) N^{-\frac{2}{d}} \leq \|u - \mathcal{I}_N^1 u\|_{L^q(\Omega)}.$$

Therefore,

$$\|u-\mathfrak{l}_{N}^{2}u\|_{L^{q}(\Omega)}\leq C_{2}(p,q,\Omega,d)C_{1}(u,q,\Omega,d)^{-1}\epsilon_{N}^{1-2\gamma}\|u-\mathfrak{l}_{N}^{1}u\|_{L^{q}(\Omega)}.$$

Since $\lim_{N\to\infty} \epsilon_N^{1-2\gamma} = 0$, we prove (17). \Box

2126

For mesh sequences satisfying *condition A*, Theorem 6 states the L^q -saturation property (17) even in the stronger form than (1): as $N \to \infty$, the parameter α can be taken arbitrarily small. For other mesh sequences the L^q -saturation property (1) remains the assumption.

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