



Relaxing the  
CFL condition

Roland Maier

Introduction

Numerical Ho-  
mogenization

Adaptive  
Meshes

Rough  
Coefficients

References

# Relaxing the CFL Condition for Explicit Numerical Wave Propagation

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Joint work with Mira Schedensack and Daniel Peterseim

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## Model problem

$$\ddot{u} - \operatorname{div} A \nabla u = f \quad \text{in } (0, T) \times \Omega$$

$$u(0) = u_0 \quad \text{in } \Omega$$

$$\dot{u}(0) = v_0 \quad \text{in } \Omega$$

$$u|_{\partial\Omega} = 0 \quad \text{in } (0, T)$$

- $\Omega \subseteq \mathbb{R}^2$  bounded, Lipschitz, polygonal
- $A \in L^\infty(\Omega; \mathbb{R}_{sym}^{2 \times 2})$
- $\alpha |\xi|^2 \leq A(x) \xi \cdot \xi \leq \beta |\xi|^2$  for all  $\xi \in \mathbb{R}^2$ , a.a.  $x \in \Omega$
- $0 < \alpha \leq \beta < \infty$

Introduction

Numerical Ho-  
mogenization

Adaptive  
Meshes

Rough  
Coefficients

References

## Problems in the context of explicit time-stepping

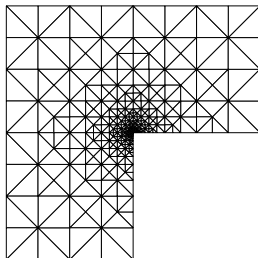
Introduction

Numerical Homogenization

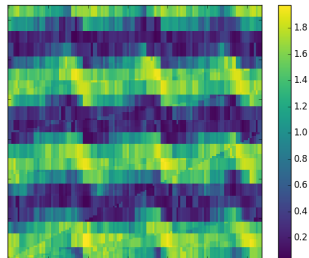
Adaptive Meshes

Rough Coefficients

References



(a) Adaptive mesh refinement



(b) Rough coefficients on a fine scale

→ CFL condition  $\Delta t \lesssim h_{min}$  leads to small time steps

## Definitions

- $V := H_0^1(\Omega)$
- $V_H \subset V$  standard  $P_1/Q_1$ -FE space based on decomposition  $\mathcal{T}_H$
- $V_h \subset V$  standard  $P_1/Q_1$ -FE space based on refinement  $\mathcal{T}_h$  of  $\mathcal{T}_H$
- $\|\bullet\| := \|\bullet\|_{L^2(\Omega)}$

Aim: Relaxed CFL condition  $\Delta t \lesssim H$

**Idea:** Construct coarse space  $\tilde{V}_H$  which accounts for fine-scale information ( $\rightarrow$  numerical homogenization)



Construction is based on  $I_H : V \rightarrow V_H$  s.t.

$$\|H^{-1}(v - I_H v)\| + \|\nabla I_H v\| \leq C \|\nabla v\| \quad \text{for all } v \in V$$

and

$$\|I_H v\| \leq C \|v\| \quad \text{for all } v \in V$$

Set  $W_h := \ker(I_H|_{V_h})$

Define projection  $\mathcal{C}v_H \in W_h$  of FE functions  $v_H \in V_H$  onto  $W_h$  by

$$(\nabla \mathcal{C}v_H, A\nabla w_h)_{L^2(\Omega)} = (\nabla v_H, A\nabla w_h)_{L^2(\Omega)}$$

for all  $w_h \in W_h$ .

With  $\tilde{V}_H := (1 - \mathcal{C})V_H$ , we have

$$V_h = \tilde{V}_H \oplus W_h \text{ and } (\nabla \tilde{V}_H, A\nabla W_h)_{L^2(\Omega)} = 0$$

Writing the model problem in variational form and applying the leapfrog scheme leads to:

Find  $(\tilde{u}_H^n)_{n=0,\dots,N} \in \tilde{V}_H$ , s.t. for  $n \geq 2$

$$\begin{aligned} & \Delta t^{-2}(\tilde{u}_H^{n+1} - 2\tilde{u}_H^n + \tilde{u}_H^{n-1}, \tilde{v}_H)_{L^2(\Omega)} + (\nabla \tilde{u}_H^n, A \nabla \tilde{v}_H)_{L^2(\Omega)} \\ & = (f(n\Delta t), \tilde{v}_H)_{L^2(\Omega)} \end{aligned}$$

for all  $\tilde{v}_H \in \tilde{V}_H$  and given  $\tilde{u}_H^0$  and  $\tilde{u}_H^1$



## Remarks

- Mass and stiffness matrices are based on the basis functions  $\tilde{\Lambda}_z = (1 - \mathcal{C})\Lambda_z$ , for  $z \in \mathcal{N}$
  - $\mathcal{C}\Lambda_z$  have global support but decay exponentially fast<sup>1</sup>
- ⇒ Localize the correctors and solve local cell problems

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<sup>1</sup>Målqvist and Peterseim 2014.



Relaxing the  
CFL condition

Roland Maier

Introduction

Numerical Ho-  
mogenization

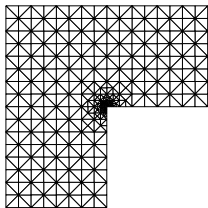
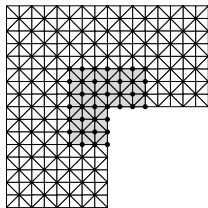
Adaptive  
Meshes

Rough  
Coefficients

References

## Setting

- $A = \mathbb{1}$
- $\Omega = (-1, 1)^2 \setminus ([0, 1] \times [-1, 0])$
- $T = 0.5, \Delta t = 0.3H$
- Initial conditions and  $f$  s.t.  
$$u(t, x) = \sin(\pi t) (r(x))^{2/3} \sin(2\theta(x)/3)$$



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<sup>2</sup>Peterseim and Schedensack 2017.



## Theoretical result

Assumptions:

- $\Delta t \lesssim H$
- exact solution  $u \in C^4$  w.r.t. time
- right-hand side  $f \in C^2$  w.r.t. time
- semi-discrete solution  $z_H \in C^4$  w.r.t. time

Then

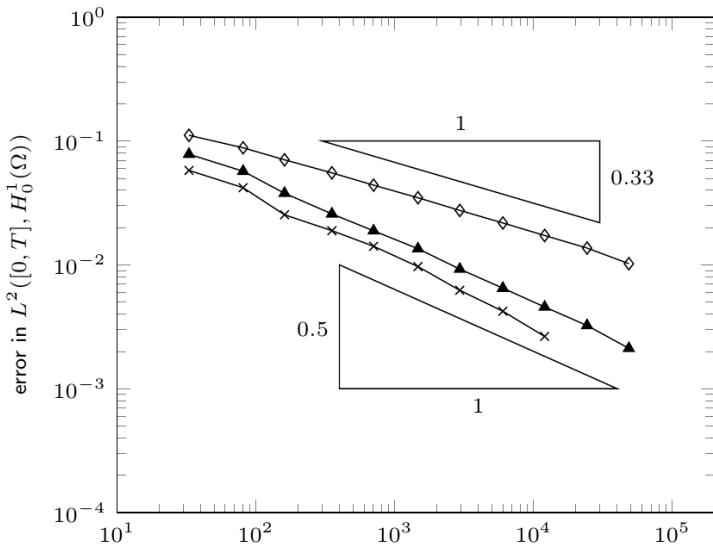
$$\begin{aligned} & \left\| \frac{\tilde{u}_H^{n+1} - \tilde{u}_H^n}{\Delta t} \right\| + \|\nabla \tilde{u}_H^{n+1}\| \\ & \leq C \left( \left\| \frac{\tilde{u}_H^1 - \tilde{u}_H^0}{\Delta t} \right\| + \|\nabla \tilde{u}_H^0\| + \|\nabla \tilde{u}_H^1\| + \sum_{k=2}^n \Delta t \|f(k\Delta t)\| \right) \end{aligned}$$

and

$$\|u - \tilde{u}_H\|_{L^2([0,T], H_0^1(\Omega))} \lesssim H + (\Delta t)^2$$



## Error plot



Relaxing the  
CFL condition

Roland Maier

## Alternative view on numerical homogenization

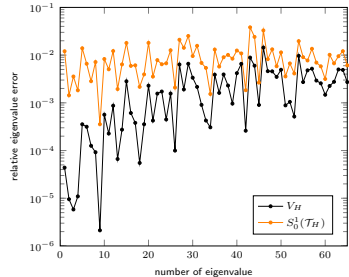
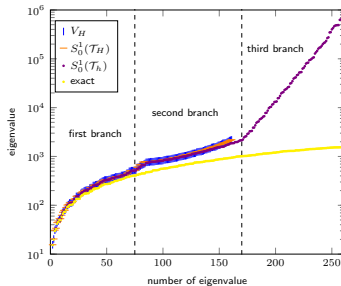
Introduction

Numerical Ho-  
mogenization

Adaptive  
Meshes

Rough  
Coefficients

References



Relaxing the  
CFL condition

Roland Maier

Introduction

Numerical Ho-  
mogenization

Adaptive  
Meshes

Rough  
Coefficients

References

## Setting<sup>3</sup>

- $A = a(x)\mathbb{1}$  with (piecewise constant) scalar function  $a$
- $\Omega = (0, 1)^2$
- $T = 1, \Delta t = 0.25H$
- Initial conditions are zero and  $f \equiv 1$

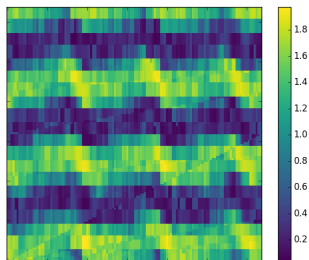


Figure:  $a(x)$

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<sup>3</sup>Abdulle and Henning 2017.

## Plots ( $H = 2^{-4}$ , $h = 2^{-7}$ , $t = 1$ )

Relaxing the CFL condition

Roland Maier

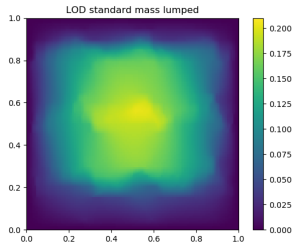
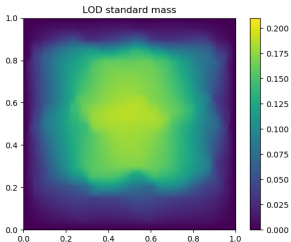
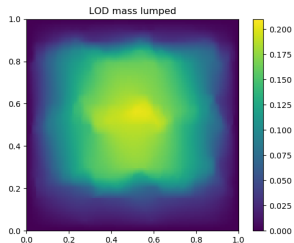
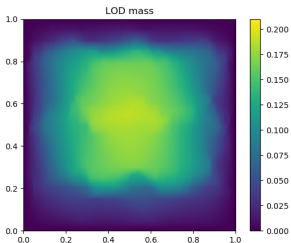
Introduction

Numerical Homogenization

Adaptive Meshes

Rough Coefficients

References



# Error plot

Relaxing the CFL condition

Roland Maier

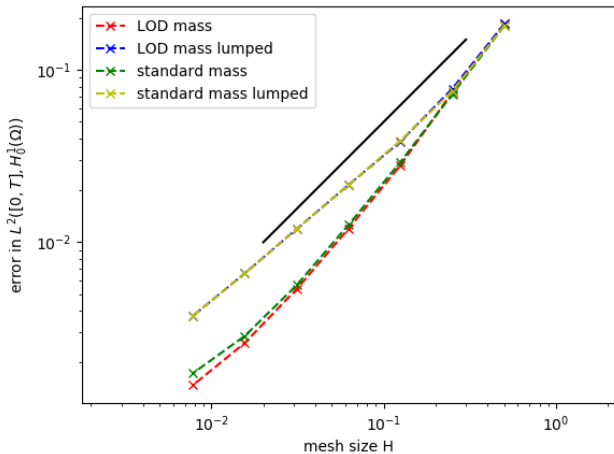
Introduction

Numerical Homogenization

Adaptive Meshes

Rough Coefficients

References







## Remarks

- symmetrized Petrov-Galerkin stiffness matrix shows similar behavior
- Coarse time steps are possible despite fine scale in space
- CFL conditions are sharp
- Open question: error estimates for rough coefficients



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- symmetrized Petrov-Galerkin stiffness matrix shows similar behavior
- Coarse time steps are possible despite fine scale in space
- CFL conditions are sharp
- Open question: error estimates for rough coefficients

**Thank you very much!**



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