

### Mathematical Modeling of Contractile and Regulatory Proteins Cooperativity in Myocardium Mechanocalcium Feedbacks

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### Mechano-electric and mechano-calcium feedbacks in exitation-contraction coupling



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#### **Twitch experimental data**



### Length-dependence in skinned cardiac muscles







Myofilament Calcium Sensitivity in Skinned Rat Cardiac Trabeculae: Role of Interfilament Spacing John P. Konhilas, Thomas C. Irving and Pieter P. de Tombe *Circ. Res.* 2002;90;59-65;



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#### Discrepancy

- High coupling between cooperativity and lenght-dependence in intact myocardium
- Low coupling in skinned heart musle





- Sulman ea. Bull Math Biol, 70(3): 910-949, 2008.
- Katsnelson ea. Prog Biophys Mol Biol, 107: 81-89, 2011.7



#### **Rheological scheme**



$$F_{muscle} = F_{XSE} \qquad F_{SE} = \beta_1 \cdot (e^{\alpha_1 (l_2 - l_1)} - 1)$$
  

$$F_{XSE} = F_{PE} + F_{CE} + k_{P_vis} \cdot v \qquad F_{PE} = \beta_2 \cdot (e^{\alpha_2 l_2} - 1)$$
  

$$F_{XSE} = F_{PE} + F_{SE} + K_{S_vis} \cdot (w - v) \qquad F_{XSE} = \beta_3 \cdot (e^{\alpha_3 l_3} - 1)$$
  

$$F_{CE} = \lambda \cdot p(v) \cdot N$$

 $F_{muscle}$  – Muscle force.

 $F_{SE}$ 

 $F_{\text{PE}}$ 

F<sub>XSE</sub>

– Force of series element SE.

– Force of extra-series element XSE.

 $\alpha_1$ ,  $\beta_1$ ,  $\alpha_2$ ,  $\beta_2$ ,  $\alpha_3$ ,  $\beta_3$  – Coefficients of nonlinear elastic elements SE, PE, and XSE.

$$\begin{pmatrix}
\frac{dN}{dt} = k_{+} \cdot M(A) \cdot n_{1}(l_{1}) \cdot L_{oz} \cdot (1-N) - k_{-} \cdot N & (1) \\
\frac{dA}{dt} = a_{on} \cdot (A_{tot} - A) \cdot Ca_{C} - a_{off} \cdot A & (2)
\end{cases}$$

Here:

 $a_{off} = \overline{a_{off}} \cdot \pi(N) \cdot e^{-k_A \cdot A}$ 

$$l_1$$
 is sarcomere length,  $v = \frac{dl_1}{dt}$ ,  $N = [Xb]$ ,  $A = [CaTnC]$ 

Where  $\pi(N)$  is an explicit function defining Xb-CaTnC cooperativity.  $e^{-k_A \cdot A}$  is an explicit function defining CaTnC-CaTnC cooperativity.

 $\pi(N), k_{+}, k_{-}, M(A), n_{1}(l_{1}), L_{oz}(l_{1})$  are explicit functions defined in detail e.g. in: T. Sulman, L.B. Katsnelson, O.Solovyova, V.S. Markhasin, Bull Math Biol, 70(3): 910-949, 2008



Now the cooperitivity reveals itself differently in steady-state and transitional processes due to the modified definition of the CaTnC dissociation rate "constant"  $a_{off}$  in the equation (2)



### Simulation of the length-dependence of 'pCa-Force' relationship in skinned cardiac muscle



*Characteristics of the 'pCa-force' relationship are produced in the model with the steady-state conditions of the cooperativity.* 



# Simulation of isometric and 4 isotonic twitches in the intact cardiac muscle



Load-dependence effect was simulated with transient conditions of cooperativity

$$\begin{cases}
\frac{dN}{dt} = k_{+} \cdot M(A) \cdot n_{1}(l_{1}) \cdot L_{oz} \cdot (1-N) - k_{-} \cdot N & (1) \\
\frac{dA}{dt} = a_{on} \cdot (A_{tot} - A) \cdot Ca_{C} - \frac{a_{off}}{A} & (2)
\end{cases}$$

$$a_{off} = \alpha \cdot [\underbrace{\overline{a_{off}} \cdot \pi(N) \cdot e^{-k_A \cdot A}}_{a_{off\,1}}] + (1 - \alpha) \cdot [\underbrace{a_{on} \cdot \overline{a_{eq\_limit}}}_{a_{off\,2}}]$$



#### **Transients in skinned muscles**



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## The modeling of transients in skinned muscles



Transients was simulated with changing of kinetic constants  $\mathbf{k}_{+}$  and  $\mathbf{k}_{-}$  in  $\frac{dN}{dt} = k_{+} \cdot M(A) \cdot n_{1}(l_{1}) \cdot L_{oz} \cdot (1-N) - k_{-} \cdot N$ 





• The refined concept of cooperativity enables us to overcome a seeming discrepancy between significant contribution of the cooperativity to the performance of the intact myocardium and experimental data obtained on skinned preparations of the heart muscle.

Conclusions

• The refined cooperativity concept outlines an approach to explain (and simulate) non-monotonic pattern of the force transient in skinned muscle preparation in response to Ca<sup>2+</sup> addition at sufficiently high temperatures.

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**Hill equation** 

 $\theta$  = fraction of the ligand-binding sites on the receptor protein which are occupied by the ligand

[L] = free (unbound) ligand concentration

 $K_d$  = dissociation constant

K<sub>A</sub> = ligand concentration producing half occupation (ligand concentration occupying half of the binding sites)

n — Hill coefficient



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### Length-dependent activation in three striated muscle types of the rat

John P. Konhilas, Thomas C. Irving \* and Pieter P. de Tombe

**Addition** 



Figure 2. Ca<sup>2+</sup>-dependent force development in skinned cardiac trabeculae, psoas and soleus muscle fibres

#### **Load-dependence of relaxation - Index**

Index of LDR estimated for 3 time constants  $\tau_{\infty}$  (top to bottom: 60 s, 100 s, 1000 s):



#### Definition of LDR index

For each afterload  $F/F_0$  (where  $F_0$  is a peak isometric force) the LDR index value is a ratio between durations of the isotonic contraction relaxation phase (under this afterload) and of the time interval within the fully isometric twitch where the force was higher than this afterload. LDR= t<sub>o</sub>/t<sub>i</sub>:



Adapted from L.E. Dobrunz, M.R. Berman. Effect of temperature on Ca<sup>2+</sup>-dependent and mechanical modulators of relaxation in mammalian myocardium. J. Mol. Cell. Cardiol. 26, 243–250, 1994.