
Reaction-diffusion equations with density dependent diffusion

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Application

- 1) Hemotaxis as chemical regulator of individual space activity
- 2) Sexual behavior in sparse populations
- 3) Genetic waves long time approximation

Basic equation

$$u_t = D(u)\nabla_x (N(u)\nabla_x u) + F(u)$$

Here $x \in \Omega \subset \mathbf{R}^n$ – space variables, $t \in \mathbf{R}_+$ – time, $u = u(t, x)$ – phase variable
internal diffusion $N(u) > N_0 > 0$ external
one $D(u) > D_0 > 0$.

Constant diffusion case

$$D(u) \equiv N(u) \equiv 1$$

Instability in bounded convex domain

If $\Omega = \text{co } \Omega \subset\subset \mathbf{R}^n$, $D(u) \equiv 1$

$$(\nabla_x u, \nu) |_{\partial\Omega} = 0, \quad \nu \perp \partial\Omega$$

Then any stationary nonconstant solution
of the basic equation is not steady (e.g. in
norm $C(\Omega)$).

Instability on real line

For $\Omega = \mathbf{R}$ the instability result is true if no one staying wave exists. E.g. it's true in the case

$$(u_1 < u_2) \ \& \ (F(u_1) = F(u_2) = 0) \Rightarrow \\ (J(u_1) \neq J(u_2)).$$

Here and later

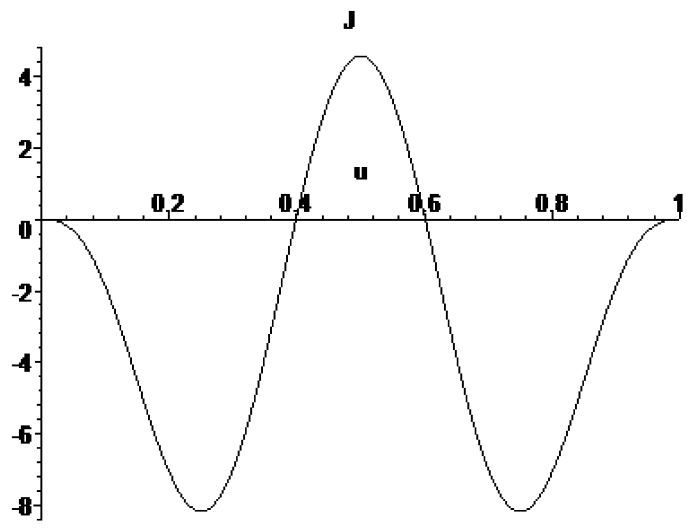
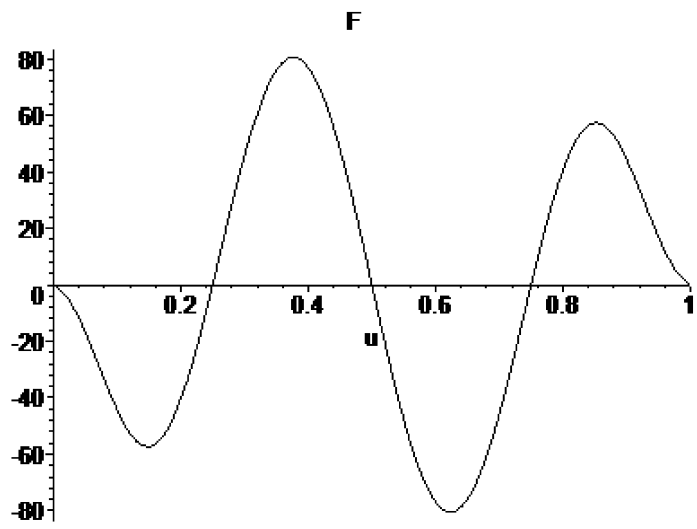
$$J(U) = \int_0^U \frac{F(u)N(u)}{D(u)} du$$

Stabilization to dominating equilibrium

Let $\Omega = \mathbf{R}^n$, $I = [0, 1]$. $F(0) \geq 0$,
 $F(1) \leq 0$.

Stationary solution $\tilde{u}(x) \equiv U \in I$, (i.e. $F(U) = 0$) – is said to be *dominating* in I ,
iff $J(U) > J(u)$ for $u \in I$, $u \neq U$. It's
stable as $(u - U)F(u) < 0$ for $u \in O(U)$,
 $O(U) \subset I$

"Almost" global attractor for solutions with
initials localized on I .



Let $\tilde{u}(x) \equiv U$ – dominating equilibrium on I , and some neighborhood $O(U) \subset I$ don't include other equilibria. Then for any segment $[A, B] \subset O(U)$, $A < U < B$ there exists $X > 0$ such that the solution $u(x, t)$ with initial $u(x, 0) \in I$ and $u(x, 0) \in [A, B]$ for $|x| < X$, stabilizes to U .

Single travelling wave

$$\Omega = \mathbf{R}, F(0) = F(1) = 0$$

Wave solution (travelling wave)

$$u(x, t) = U(\xi), \quad \xi = x + ct, \quad U_\xi > 0$$

$$U(-\infty) = 0, \quad U(+\infty) = 1, \quad c \in \mathbf{R}$$

$$P(\xi) = N(U(\xi))U_\xi(\xi)$$

$$\begin{cases} U_\xi = \frac{P}{N(U)} \\ P_\xi = \frac{cP}{N(U)D(U)} - \frac{F(U)}{D(U)}. \end{cases}$$
$$\frac{dP}{dU} = \frac{c}{D(U)} - \frac{F(U)N(U)}{D(U)P}$$

$$J(1) = c \int_0^1 \frac{P(U)}{D(U)} dU \Rightarrow \text{sign } J(1) = \text{sign } c$$

Asymptotic solutions – ones, meeting the system and one of boundary conditions. Comparison technique for them results in existence and uniqueness theorems.

a) *Kolmogorov case*

$$F(u) > 0, u \in (0, 1)$$

$$\forall c \geq c^*, c^* \in [c_m, c_M],$$

$$c_m = 2\sqrt{N(0) D(0) F_u(0)},$$

$$c_M = 2 \sqrt{\sup_{u \in (U_1, U_2)} \left(N(u) F(u) / \int_{U_1}^u \frac{dv}{D(v)} \right)}$$

b) *Trigger case*

$$F(\varepsilon) < 0, F(1 - \varepsilon) > 0, \varepsilon > 0$$

$$(i) \& (ii) \Rightarrow \exists! c \geq 0$$

$$i) \forall u \in (0, 1), \quad J(u) < J(1),$$

$$ii) \bar{u} \in (0, 1) \& F(\bar{u}) = 0 \Rightarrow J(\bar{u}) < 0$$

P.S. 1) In (ii) it's enough to check zeros \bar{u} with:

$$F(\bar{u} - \varepsilon) > 0, \quad \forall \varepsilon \in (0, \varepsilon_o), \varepsilon_o > 0$$

2) If $J(1) < 0$ the change

$$\hat{c} = -c, \quad \hat{x} = -x, \quad \hat{u} = 1-u, \quad \hat{F} = -F(1-\hat{u}),$$

$$\hat{D}(\hat{u}) = D(1 - \hat{u}), \quad \hat{N}(\hat{u}) = N(1 - \hat{u}),$$

Trigger wave chains

Zero \bar{u} is stable (with respect to ODE $\frac{du}{dt} = F(u)$) iff

$$\pm F(\bar{u} \pm \varepsilon) \leq 0, \forall \varepsilon \in (0, \varepsilon_o), \varepsilon_o > 0$$

Let $0 = u_0 < u_1 < \dots < u_k = 1$ – isolated zeros, $u_i, i \geq 1$ – stable

$$i < j, c_{ij} \in \mathbf{R} :$$

$$U(-\infty) = u_i, U(+\infty) = u_j$$

If for $0 \leq q < m < l \leq k \exists c_{qm} < c_{ml}$.
Then $\exists c_{ql} \in (c_{qm}, c_{ml})$.

Minimal chains

For any full set of zeros

$$\{u_i\}, u_1 < u_2 < \dots < u_k$$

$$i_j \in \{1, \dots, k\} : \exists! \{c_{i_j i_{j+1}} \geq c_{i_{j+1} i_{j+2}}\}$$

Kolmogorov wave chains

u_0 – unstable $\exists c_{0j} \in I_j, j \geq 2$ where by induction $I_j = [c_K^j, \hat{c}^j)$, with \hat{c}^j – minimal velocity in trigger chain for $\{u_p\}$. $p = 1, \dots, j$, and $c_K^j \in I_{j'}, j' < j$.

Stabilization to wave chains

$$F(0) = F(1) = 0,$$

$$u_x(x, 0) \geq 0 \Rightarrow u_x(x, t) > 0$$

for $Q(u, t) = u_x(u, t)$

$$\begin{aligned} Q_t &= Q^2 \left(D(QN)_u + \frac{F}{Q} \right)_u = \\ &= Q^2 (D(QN)_u)_u + F_u Q - F Q_u \end{aligned}$$

$$\pm \frac{\alpha_{\pm}(t)}{dt} = \pm F(\alpha_{\pm}) \geq 0$$

$$\exists! Q(u, t), Q(\pm\alpha_{\pm}(t), t) = 0$$

$$\int_{\alpha_{\pm}(t)}^{\alpha_{\pm}(t) \mp \varepsilon} \frac{du}{Q(u, t)} = \infty, t > 0$$

$$Q(u, 0) \geq 0, u \in [0, 1]$$

$$\& \neq 0, u \in (\alpha_-(0), \alpha_+(0))$$

Sub- & supersolutions

$(Q_t =) \rightarrow$

$$\begin{cases} (Q_t \leq) - \text{regular subsolution (RDS)} \\ (Q_t \geq) - \text{regular supersolution (RUS)} \end{cases}$$

Maximum of RDS is a subsolution (DS).

Minimum of RUS is a supersolution (US).

1) solution is both RDS and RUS

2) US \geq DS if at $t = 0$

3) If $Q_+(u) \geq 0$ – stationary US (SUS)

and not a solution and $Q(u, t)$ with $Q(u, 0) =$

$Q_+(u)$ – solution such that on boundaries $\frac{d}{dt}Q(0, t) \leq 0$, $\frac{d}{dt}Q(1, t) \leq 0$,

then $\frac{\partial}{\partial t}Q(u, t) \leq 0$, $\neq 0$ if $Q(u, t) \neq 0$.
So, $Q(u, \bar{t})$ for $\bar{t} > 0$ is SUS.

4) If $Q_-(u) \leq Q(u, \bar{t}) \leq Q_+(u)$ at some $\bar{t} \geq 0$, and $\exists! \bar{Q}(u)$ – SS, such that

$$Q_-(u) \leq \bar{Q}(u) \leq Q_+(u),$$

then $Q(u, t) \rightarrow \bar{Q}(u)$, $t \rightarrow \infty$.

Convergence on phase plane results in convergence to shifted wave with proper velocity.

Supersolutions in single wave case

In case $F(0) = F(1) = 0$ let

$$M > \sup_u \max\{Q(u, 0), Q_i(u)\},$$

with $Q_i(u)$ – all possible travelling wave

solutions on $(0, 1)$,

$$\hat{Q}(u) = M + \int_0^u \frac{1-v}{D(v)} dv,$$

$$A^2 \geq \sup_u \left\{ \left| \left(\frac{F(u)N(u)}{\hat{Q}(u)} \right)_u \right| \right\}$$

$\bar{Q}(u) = A \frac{\hat{Q}(u)}{N(u)}$ – SUS, so that the solution $Q_M(u, t)$ with $Q_M(u, 0) = \bar{Q}(u)$ and

$$Q_M(0, t) = Q_M(1, t) = 0,$$

for $t > 0$, is nonincreasing

Subsolutions in single wave case

1) Basic DS.

On connected sets $I_{\pm} \subset (0, 1)$, where $\pm F(u) > 0$.

a) $\omega \in I_-$.

$$Q_-(u) = \max\{0, \varepsilon F(u)(\omega - u)\}, \varepsilon > 0.$$

b) $\omega \in I_+$.

$Q_-(u) = \max\{0, \Phi(u)\}$ with rather small asymptotic solution $\Phi(u)$, leaving unstable zero.

Bridges over unstable zero \hat{u}

$$Q_-(u, \hat{u}, \varepsilon) = \frac{\sqrt{2(J(\hat{u}) + \varepsilon - J(u))}}{N(u)}$$

Bridges over stable zero \hat{u}

$\hat{u} \in (0, 1)$ – single inner stable zero.
 $F'(\bar{u}) < 0$.

1) $c_1 \geq c_2$ – combinatorics of single waves and zeros.

2) Let $c_1 < c_2$, with the first wave entering an equilibrium \hat{u} , and the second one leaving it. Then $Q(\hat{u}, 0) > 0$ results in $Q(\hat{u}, t) > \varepsilon > 0$, so under ε one can construct the bridge – wave solution with velocity $c \in (c_1, c_2)$

Super- and subsolutions in Kolmogorov case $F_u(0) > 0$

from characteristic equation

$$c = \tilde{c}(q) = qD(0)N(0) + \frac{F_u(0)}{q},$$

with $\tilde{q}(c) = \min\{q > 0 : \tilde{c}(q) = c\}$

Function $c = \tilde{c}(q) > 0$ has minimum c_m

at $\hat{q} = \sqrt{\frac{F_u(0)}{(D(0)N(0))}}$

1) In the case with minimal velocity c^* one can get $\Phi(u) = \max \Phi_\lambda(u)$ with $\Phi_\lambda(u) \leq Q(u, 0)$ – trajectories, leaving unstable zero with $c \rightarrow c^* + 0$.

2) Real wave velocity c is defined by initial asymptotic at $u = 0$.

E.g. if $\exists q = \frac{dQ(u,0)}{du}|_{u=0} \in [0, q^*]$, for

$q^* \leq \hat{q}$ such that $c^* = \tilde{c}(q^*) \geq c_m$ then $c = \tilde{c}(q) \geq c^*$. Otherwise ($q > q^*$) one has $c = c^*$.

DS are constructed as above. US for proper value of q is constructed at later time moment.

The case of minimal velocity

Theorem Let nonnegative continuous function $Q(u, 0)$ is positive over $(0, \beta)$, with $F(\beta) > 0$ or $\beta \in \{u_i\}$, $i = 1, \dots, k$. Then under the inequality

$$\liminf_{u \rightarrow +0} \frac{Q(u, 0)}{u} \geq \tilde{q}(c^*)$$

the true solution $Q(u, t)$ converges on phase plain for $t \rightarrow +\infty$ to Kolmogorov's minimal true chain on interval $(0, u_+)$, where $u_+ = \min u_i \geq \beta$, $i = 1, \dots, k$, with minimal first wave velocity c^{jM} .

Conclusion. In the case of strictly increasing over x initial $u(x, 0)$, vanishing at some finite \bar{x} with $u_x(\bar{x}, 0) > 0$, or else with $u_x(x, 0) > 0$ and $u_{xx}(x, 0) \geq -\delta$ at $x \in (\bar{x}, \bar{x} + \varepsilon)$ for some $\varepsilon, \delta > 0$, the first wave velocity would be minimal, i.e. equal c^{JM} .

The case of non-minimal velocity

For $c > c^*$ let $C_c(u)$ be the wave with velocity c .

Theorem. Let $\tilde{Q}(u, 0) = u(q + g(u))$ with $q \in (0, \tilde{q}(c^*))$ and continuous over $[0, 1]$ function $g(u) = o(1)$, for which the integral $\int_{+0}^1 \frac{g(u)}{u} du$ converges.

Then the true solution $\tilde{Q}(u, t)$ converges to the wave $C_{\tilde{c}(q)}(u)$ for $t \rightarrow +\infty$ in the following sence.

There exist functions $Q_{\pm}(u, t)$ such that $0 \leq Q_{-}(u, t) \leq Q(u, t) \leq Q_{+}(u, t)$, whereas $Q_{-}(u, t) \leq C_{\tilde{c}(q)}(u)$ converges to $C_{\tilde{c}(q)}(u)$ uniformly on compacts $I \subset (0, 1)$, and for $Q_{+}(u, t) \geq C_{\tilde{c}(q)}(u)$ in the metric $\rho^t(Q_1, Q_2) =$

$$\int_t^{+\infty} \int_0^1 \frac{F(u)}{D(u)} \left| \frac{1}{Q_1(u, \tau)} - \frac{1}{Q_2(u, \tau)} \right| dud\tau$$

$$\rho^t \left(Q_{+}(u, t), C_{\tilde{c}(q)}(u) \right) \rightarrow 0$$

convergence takes place.

The leader selection in a diffusion model of competing species.

$$x \in \mathbf{R}, i = 1, \dots, N, u^i(x, t) \geq 0.$$

$$D^i > 0, F^i(u) = u^i \left(M^i - \sum_{j=1}^N \gamma_{ij} u^j \right),$$

$u = (u^1, \dots, u^N)$ – population densities,

$M = (M^1, \dots, M^N) > 0$ – malthusian

parameters, $\Gamma = \|\gamma_{ij}\|$ – competition matrix,

$\gamma_{ii} > 0$.

Reaction-diffusion system:

$$u_t^i = D^i u_{xx}^i + u^i \left(M^i - \sum_{j=1}^N \gamma_{ij} u^j \right)$$

$u^i(x, 0) \geq 0$, The support

$$S^i = \text{supp } u^i(x, 0) = \text{cl}\{x : u^i(x, 0) > 0\} \neq \emptyset.$$

$$S = \text{co} \left(\bigcup_{i=1}^N S^i \right) - \text{seat is bounded.}$$

(H1) The common ecological niche hypothesis:
 $\gamma_{ij} = \alpha_i \beta_j$, & $m^i = \frac{M^i}{\alpha_i}$ are different.

$$\text{For } N = 1 \quad c^1 = 2\sqrt{D^1 M^1}, \quad \hat{u}^1 = \frac{M^1}{\gamma_{11}}.$$

The spesies $i_1 \in \{1, \dots, N\}$ is a *leader*,
 $\forall X > 0 \exists \hat{x} > X: \exists t_j > 0:$

- 1) $u^{i_1}(\hat{x}, t_j) > \delta^i;$
- 2) $u^k(x, t_j) < \delta^k \quad \forall k \neq i_1 \text{ and } x \geq \hat{x}.$

(H2) Solution of the problem $i_1 \in \{1, \dots, N\}$,

$$\sqrt{D^{i_1} M^{i_1}} = \max_i \left\{ \sqrt{D^i M^i} \right\}.$$

is unique.

Theorem (H1), (H2) \Rightarrow The leader exists
and its number does not depend on initial
finite distributions

Example: Diffusion model of genetic waves

Hypotheses

1. The Population is distributed in space with one variable $x \in \mathbf{R}$.
2. Phenotypic particularities differ due to one two-allelic gene with alleles A and a .
3. Total number of A and a alleles of fertile individuals is constant
 $p(t, x) + q(t, x) = 1$.

4. Changes of alleles A and a number occurs through their carriers with genotypes AA , Aa , and aa having fitness (the alive factors to maturation age, i.e. from conception to fertile stage) α , β , γ . The departure rate from fertile stage (death-rate + aging) is constant.
5. Locally over x the hypothesis about full panmixia is fulfilled.
6. Crossbreeding is realized via the gametes spatial carrying, and not depends on genotype.

Integral model

The long-range genetic action operator at maturation time $h = 1$

$$K(p)(x, t) = \int_{-\infty}^{+\infty} k(x.\xi)p(\xi, t)d\xi$$

$$k(x.\xi) = \frac{e^{-\frac{(x-\xi)^2}{2\sigma^2}}}{\sqrt{2\pi\sigma^2}}, \quad K(1) = 1$$

(3) If $\varphi = K(p)$, $\psi = K(q) = 1 - \varphi$, $u_A = p\varphi$, $u_{Aa} = p\psi + q\varphi$, $u_a = q\psi$, that

$$\begin{cases} p_t = 2\alpha u_A + \beta u_{Aa} - pr, \\ q_t = \beta u_{Aa} + 2\gamma u_a - qr, \end{cases}$$

where $r : p + q = 1$ so $r = r(p + q) = 2(\alpha u_A + \beta u_{Aa} + \gamma u_a)$.

$$p_t = \varphi R(p) + [\beta p(q - p) - 2pq\gamma],$$

$$R(p) = 2pq(\alpha + \gamma) + \beta(q - p)^2 > 0$$

PDE approximation

Decomposition

$$p(\xi, t) = p(x, t) + \frac{\partial p(x, t)}{\partial x}(\xi - x) + \frac{1}{2} \frac{\partial^2 p(x, t)}{\partial x^2}(\xi - x)^2 + \dots$$

gives for small $\sigma > 0$

$$K(p)(x, t) = p(x, t) + \frac{\sigma^2}{2} \frac{\partial^2 p(x, t)}{\partial x^2} + \dots,$$

and equation

$$p_t = D(p)p_{xx} + F(p),$$

where $D(p) = \frac{\sigma^2}{2}R(p)$,

$$F(p) = pR(p) + [\beta p(q - p) - 2pq\gamma] = 2pq[\alpha p - \gamma q + \beta(q - p)].$$

Main results

Three equilibria:

$$p_0 = 0, \quad p_1 = 1, \quad p^* = \frac{\gamma - \beta}{\alpha + \gamma - 2\beta}.$$

$$J = \int_0^1 \frac{F(u)}{D(u)} du, \quad \text{sign } J = \text{sign} \left(\frac{1}{2} - p^* \right)$$

$$\delta = \frac{\alpha + \gamma}{2}. \quad \alpha > \gamma$$

Intervals for β :

$$(-\infty, \gamma), \quad (\gamma, \delta), \quad (\delta, \alpha), \quad (\alpha, +\infty)$$

$R(p)$ concave $\delta > \beta$, convex $\delta < \beta$.

1. $\beta < \gamma$.

$$F'(0) = 2(\beta - \gamma) < 0, \quad F'(1) = 2(\beta - \alpha) < 0, \quad p^* \in \left(0, \frac{1}{2} \right), \quad J > 0$$

The Wave solution = genetic wave of spreading of more strong allele A .

2. $\gamma < \beta < \delta$.

$F'(0) > 0$, $F'(1) < 0$, and $p^* < 0$ so $F(p) > 0$ under $p \in (0, 1)$. Wave solutions with velocity $c \geq c^* \geq c_K$, where c^* – minimum, but

$$c_K = 2\sqrt{D(0)F'(0)} = 2\sigma\sqrt{\beta(\beta - \gamma)}$$

– Kolmogorov's velocity.

3. $\delta < \beta < \alpha$.

$F'(0) > 0$, $F'(1) < 0$, and $p^* > 1$, once again $F(p) > 0$ under $p \in (0, 1)$.

Since function $D(p)$ is convex (maximum on the end of the interval $(0, 1)$), but

$$F'(p) > 0 \Rightarrow F''(p) < 0$$

, that $C^* = C_K$

4. $\beta > \alpha$.

$F'(0) > 0$, $F'(1) > 0$. Chain of two waves, scattering from $p^* \in \left(\frac{1}{2}, 1\right)$. The velocities value spread from

$$c_K^0 = 2\sqrt{D(0)F'(0)} = 2\sigma\sqrt{\beta(\beta - \gamma)}$$

and

$$c_K^1 = 2\sqrt{D(1)F'(1)} = 2\sigma\sqrt{\beta(\beta - \alpha)}$$

to $+\infty$. Minimal value of the velocity follows from implication

